

13. (a) The motion repeats every 0.500 s so the period must be $T = 0.500$ s.

(b) The frequency is the reciprocal of the period: $f = 1/T = 1/(0.500 \text{ s}) = 2.00$ Hz.

(c) The angular frequency ω is $\omega = 2\pi f = 2\pi(2.00 \text{ Hz}) = 12.6$ rad/s.

(d) The angular frequency is related to the spring constant k and the mass m by $\omega = \sqrt{k/m}$. We solve for k and obtain

$$k = m\omega^2 = (0.500 \text{ kg})(12.6 \text{ rad/s})^2 = 79.0 \text{ N/m}.$$

(e) Let x_m be the amplitude. The maximum speed is

$$v_m = \omega x_m = (12.6 \text{ rad/s})(0.350 \text{ m}) = 4.40 \text{ m/s}.$$

(f) The maximum force is exerted when the displacement is a maximum and its magnitude is given by $F_m = kx_m = (79.0 \text{ N/m})(0.350 \text{ m}) = 27.6$ N.

41. (a) A uniform disk pivoted at its center has a rotational inertia of $\frac{1}{2}Mr^2$, where M is its mass and r is its radius. The disk of this problem rotates about a point that is displaced from its center by $r + L$, where L is the length of the rod, so, according to the parallel-axis theorem, its rotational inertia is $\frac{1}{2}Mr^2 + \frac{1}{2}M(L+r)^2$. The rod is pivoted at one end and has a rotational inertia of $mL^2/3$, where m is its mass. The total rotational inertia of the disk and rod is

$$\begin{aligned} I &= \frac{1}{2}Mr^2 + M(L+r)^2 + \frac{1}{3}mL^2 \\ &= \frac{1}{2}(0.500 \text{ kg})(0.100 \text{ m})^2 + (0.500 \text{ kg})(0.500 \text{ m} + 0.100 \text{ m})^2 + \frac{1}{3}(0.270 \text{ kg})(0.500 \text{ m})^2 \\ &= 0.205 \text{ kg} \cdot \text{m}^2. \end{aligned}$$

(b) We put the origin at the pivot. The center of mass of the disk is

$$\ell_d = L + r = 0.500 \text{ m} + 0.100 \text{ m} = 0.600 \text{ m}$$

away and the center of mass of the rod is $\ell_r = L/2 = (0.500 \text{ m})/2 = 0.250 \text{ m}$ away, on the same line. The distance from the pivot point to the center of mass of the disk-rod system is

$$d = \frac{M\ell_d + m\ell_r}{M + m} = \frac{(0.500 \text{ kg})(0.600 \text{ m}) + (0.270 \text{ kg})(0.250 \text{ m})}{0.500 \text{ kg} + 0.270 \text{ kg}} = 0.477 \text{ m}.$$

(c) The period of oscillation is

$$T = 2\pi \sqrt{\frac{I}{(M + m)gd}} = 2\pi \sqrt{\frac{0.205 \text{ kg} \cdot \text{m}^2}{(0.500 \text{ kg} + 0.270 \text{ kg})(9.80 \text{ m/s}^2)(0.477 \text{ m})}} = 1.50 \text{ s}.$$

22. The statement that “the spring does not affect the collision” justifies the use of elastic collision formulas in section 10-5. We are told the period of SHM so that we can find the mass of block 2:

$$T = 2\pi\sqrt{\frac{m_2}{k}} \Rightarrow m_2 = \frac{kT^2}{4\pi^2} = 0.600 \text{ kg.}$$

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At this point, the rebound speed of block 1 can be found from Eq. 10-30:

$$|v_{1f}| = \left| \frac{0.200 \text{ kg} - 0.600 \text{ kg}}{0.200 \text{ kg} + 0.600 \text{ kg}} \right| (8.00 \text{ m/s}) = 4.00 \text{ m/s}.$$

This becomes the initial speed v_0 of the projectile motion of block 1. A variety of choices for the positive axis directions are possible, and we choose left as the $+x$ direction and down as the $+y$ direction, in this instance. With the “launch” angle being zero, Eq. 4-21 and Eq. 4-22 (with $-g$ replaced with $+g$) lead to

$$x - x_0 = v_0 t = v_0 \sqrt{\frac{2h}{g}} = (4.00 \text{ m/s}) \sqrt{\frac{2(4.90 \text{ m})}{9.8 \text{ m/s}^2}}.$$

Since $x - x_0 = d$, we arrive at $d = 4.00 \text{ m}$.

51. This is similar to the situation treated in Sample Problem — “Physical pendulum, period and length,” except that O is no longer at the end of the stick. Referring to the center of mass as C (assumed to be the geometric center of the stick), we see that the distance between O and C is $h = x$. The parallel axis theorem (see Eq. 15-30) leads to

$$I = \frac{1}{12} mL^2 + mh^2 = m \left(\frac{L^2}{12} + x^2 \right).$$

Equation 15-29 gives

$$T = 2\pi \sqrt{\frac{I}{mgh}} = 2\pi \sqrt{\frac{\left(\frac{L^2}{12} + x^2\right)}{gx}} = 2\pi \sqrt{\frac{(L^2 + 12x^2)}{12gx}}.$$

(a) Minimizing T by graphing (or special calculator functions) is straightforward, but the standard calculus method (setting the derivative equal to zero and solving) is somewhat awkward. We pursue the calculus method but choose to work with $12gT^2/2\pi$ instead of T (it should be clear that $12gT^2/2\pi$ is a minimum whenever T is a minimum). The result is

$$\frac{d\left(\frac{12gT^2}{2\pi}\right)}{dx} = 0 = \frac{d\left(\frac{L^2}{x} + 12x\right)}{dx} = -\frac{L^2}{x^2} + 12$$

which yields $x = L/\sqrt{12} = (1.85 \text{ m})/\sqrt{12} = 0.53 \text{ m}$ as the value of x that should produce the smallest possible value of T .

(b) With $L = 1.85 \text{ m}$ and $x = 0.53 \text{ m}$, we obtain $T = 2.1 \text{ s}$ from the expression derived in part (a).

17. (a) Equation 15-8 leads to

$$a = -\omega^2 x \Rightarrow \omega = \sqrt{\frac{-a}{x}} = \sqrt{\frac{123 \text{ m/s}^2}{0.100 \text{ m}}} = 35.07 \text{ rad/s}.$$

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Therefore, $f = \omega/2\pi = 5.58 \text{ Hz}$.

(b) Equation 15-12 provides a relation between ω (found in the previous part) and the mass:

$$\omega = \sqrt{\frac{k}{m}} \Rightarrow m = \frac{400 \text{ N/m}}{(35.07 \text{ rad/s})^2} = 0.325 \text{ kg}.$$

(c) By energy conservation, $\frac{1}{2} kx_m^2$ (the energy of the system at a turning point) is equal to the sum of kinetic and potential energies at the time t described in the problem.

$$\frac{1}{2} kx_m^2 = \frac{1}{2} mv^2 + \frac{1}{2} kx^2 \Rightarrow x_m = \sqrt{\frac{m}{k} v^2 + x^2}.$$

Consequently, $x_m = \sqrt{(0.325 \text{ kg} / 400 \text{ N/m})(13.6 \text{ m/s})^2 + (0.100 \text{ m})^2} = 0.400 \text{ m}$.

34. We note that the spring constant is

$$k = 4\pi^2 m_1 / T^2 = 1.97 \times 10^5 \text{ N/m.}$$

It is important to determine where in its simple harmonic motion (which “phase” of its motion) block 2 is when the impact occurs. Since $\omega = 2\pi/T$ and the given value of t (when the collision takes place) is one-fourth of T , then $\omega t = \pi/2$ and the location then of block 2 is $x = x_m \cos(\omega t + \phi)$ where $\phi = \pi/2$ which gives $x = x_m \cos(\pi/2 + \pi/2) = -x_m$. This means block 2 is at a turning point in its motion (and thus has zero speed right before the impact occurs); this means, too, that the spring is stretched an amount of $1 \text{ cm} = 0.01 \text{ m}$ at this moment. To calculate its after-collision speed (which will be the same as that of block 1 right after the impact, since they stick together in the process) we use momentum conservation and obtain $v = (4.0 \text{ kg})(6.0 \text{ m/s})/(6.0 \text{ kg}) = 4.0 \text{ m/s}$. Thus, at the end of the impact itself (while block 1 is still at the same position as before the impact) the system (consisting now of a total mass $M = 6.0 \text{ kg}$) has kinetic energy

$$K = \frac{1}{2}(6.0 \text{ kg})(4.0 \text{ m/s})^2 = 48 \text{ J}$$

and potential energy

$$U = \frac{1}{2}kx^2 = \frac{1}{2}(1.97 \times 10^5 \text{ N/m})(0.010 \text{ m})^2 \approx 10 \text{ J,}$$

meaning the total mechanical energy in the system at this stage is approximately $E = K + U = 58 \text{ J}$. When the system reaches its new turning point (at the new amplitude X) then this amount must equal its (maximum) potential energy there: $E = \frac{1}{2}(1.97 \times 10^5 \text{ N/m}) X^2$.

Therefore, we find

$$X = \sqrt{\frac{2E}{k}} = \sqrt{\frac{2(58 \text{ J})}{1.97 \times 10^5 \text{ N/m}}} = 0.024 \text{ m.}$$